## EXCELLENCE CLYNG IN MOTION

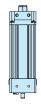
# AXIOM PV CONTROLLER/DRIVE & SW44 ACTUATOR



Integrated PLC performs real-time scans on a separate thread and communicates through software rather than physical wiring. Windows®-based software utilizes a point and click sequential program and PLC ladder logic editor, allowing programming without learning code.



Designed for the most exacting applications, the SW44 is a field-proven electric cylinder that is built to last. Properly applied, the SW44 will deliver millions of maintenance-free cycles.



## **SW44 Actuator**

### **OVERVIEW**



**SW44** 

OVERVIEW DIMENSIONS ORDERING

#### FEATURES, ADVANTAGES, BENEFITS

FEATURE	ADVANTAGE	BENEFIT
Millions of cycles	Long Life	Lower Operating Cost
Zero Maintenance	No System Down Time	Higher Productivity
Actuator/Motor/Feedback Integrated in One Unit	Compact Envelope	Application Flexibility
8 Pole Hollow Core Motor	Short Body Length	Application Flexibility
High Force & High Speed	with Controlled Motion	Hydraulic Replacement
Controlled Motion Profile	Fast Move to Position with Reduced Impact Speed	Fast Cycle Time with Less Parts Stress
Ball Screw or Roller Screw	Lower Cost Higher Force	Application Flexibility
Manual Override	In 2 Locations	Use in Power Loss

#### SPECIFICATIONS

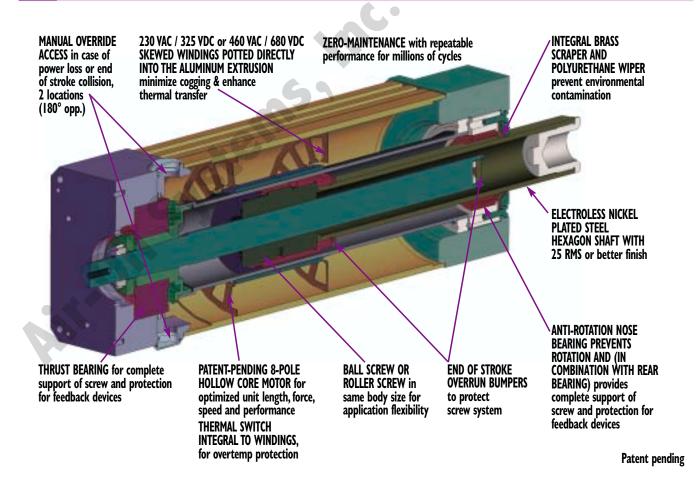
FEATURES	SW SERIES	
Operating Force	ROLLER SCREW Up to 2500 lbf [11.1 kN]	BALL SCREW Up to 1000 lbf [4.4 kN]
Peak Force*	4400 lbf [19.6 kN]	
Continuous Force**	1850 lbf [8.2 kN]	
Peak Speed (at 2000 lbf)	13 in/sec [330.2mm/sec]	
Feedback Device	Quantum Quadrature Encoder - Others Available on Regest, Contact Factory	
Weight (with 6" stroke)	31 lbs [14.1 kg]	

<sup>\*</sup>Peak Force is a result of the limit of the drive

#### **DRIVE CONSIDERATIONS**

All servo actuators are tested with the Tol-O-Matic AxiomPlus<sup>TM</sup> drive/controller before leaving the factory and are validated to meet performance specifications. Actual performance may be affected by the choice of the motor drive.

#### SW FEATURES



<sup>\*\*</sup>Continuous Force is achieved with actuator surface temp. less than 155° F (69° C)





SW44

**OVERVIEW** 

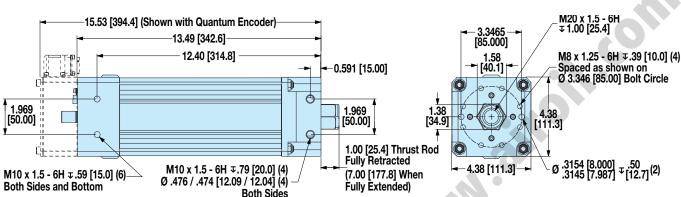
#### **DIMENSIONS (SHOWN WITH FEEDBACK DEVICE)**

3D SOLID MODELS AVAILABLE - CONTACT TOL-O-MATIC

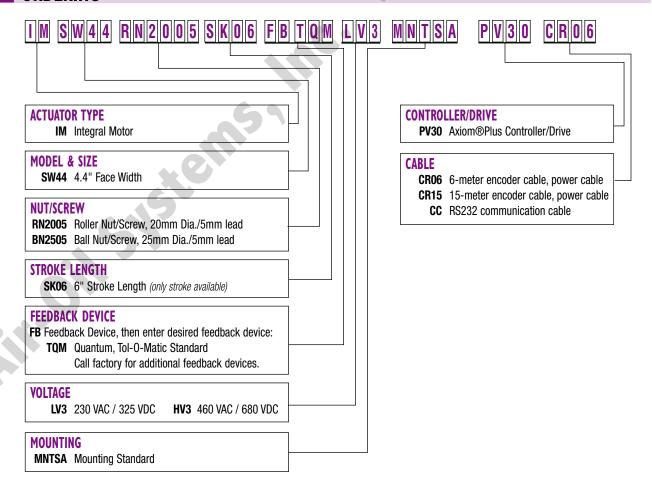
NOTE: Base actuator shown with feedback device. Dimensions are for reference only. Contact Tol-O-Matic for solid models

Dimensions in inches [Dimensions in millimeters]





#### **ORDERING**







**FEATURES** SPECIFI-CATIONS

DIMENSIONS

PLC /

SEQUENTIAL PROGRAM **EDITORS ORDERING** 



- Real-time scan supervisory function continuous from power-up
- Typical scan time of 2-4 milliseconds
- Ladder logic allows 175 rungs, 4 lines deep, 5 input operations, and an output coil
- Operations include: normally-open, normally-closed, logical invert, one-shot, output coil, latch, unlatch, timers and counters
- 64 character rung descriptor downloaded and uploaded with program
- Internal bit-flags for information transfer between controller and PLC

#### **MOTION CONTROLLER:**

- 1.5 axis (gearing to auxiliary axis)
- Commands include: absolute, incremental and velocity moves, branch to labels, subroutine calls, repeat loops, time delays, wait on conditions/inputs, output/flag control and parameter value changes including torque limit, following error, position band, follower gear ratio, maximum velocity, analog position and analog velocity
- Event triggering based on intermediate positions
- Motion pause and resume
- Comment lines and labels down-loaded and uploaded with program

#### DRIVE:

- PV series drives use space vector commutation providing better bus voltage utilization than traditional sine drives for improved speed/torque curves
- Flux vector current control provides accurate high bandwidth control of torque producing current for better efficiency and more torque over the full speed range than with traditional sine drives
- Drives Tol-O-Matic SW44 and MRV series brushless servo motors or can be configured for customer supplied brushless servo motors
- Autophasing eliminates the need for Hall sensors in motors

#### GENERAL:

- Modbus RTU and ASCII interface
- Pluggable screw terminal connectors eliminate the need for special connectors and secondary breakout terminal strips
- Short circuit, over current and over voltage protection prevents drive damage
- 25W or 50W internal regeneration
- 14 bit analog input
- External regeneration connections
- CW/CCW travel limit inputs
- Fault, enabled, and in-position outputs
- 3A brake relay
- 3 second peak ratings



## **Axiom PV30**

### **SPECIFICATIONS**





AXIOM PV30

FEATURES
SPECIFICATIONS
DIMENSIONS
PLC /
SEQUENTIAL
PROGRAM
EDITORS

**ORDERING** 

SPECIFICATIONS		Axiom® PV30 Drive	
	Weight	12.5 lbs (5.66 kg)	
Power	Peak Output Current:	30 Amps	
	Continuous Output Current:	15 Amps	
Continuous Output Power:		4.2 kW	
Input Voltage:		95 Vac -250 Vac 10; 95 Vac - 250 Vac 30 (voltage range is switch selectable)	
Input Frequency:		47Hz - 63Hz	
User P	rogramming		
Language/Programming Environment:		Tol-O-Motion™ windows-based software with point and click sequential program and PLC ladder logic editors	
Firmware Field Upgradeable:		YES	
User Program Storage Capacity:		500 lines of graphic-based, high-level sequential motion and control instructions with unlimited subroutine calls.	
PLC	Connection/Capabilities:	Internal PLC with typical real-time scan of 2-4 msec, 10-12 msec for programs of maximum capacity; 15 inputs	
Interfa	ace Interfaces supported:	Modbus RTU ASCII	

SPECIFICATIONS	Axiom® PV30 Drive	
Inputs/Outputs		
General-Purpose Digital Inputs:	15 optically isolated 5-25 Vdc	
Inputs/Outputs:	Sinking/sourcing selectable	
Analog Input:	1 14 bit ±10V Differential	
General-Purpose Digital Outputs:	8 optically isolated, 5-25 Vdc, 20 mA max.	
Communications:	Serial: RS-232, 19,200 baud rate	
Motor Feedback	• •	
Input Modes:	Incremental with index	
Maximum Input Frequency:	4 MHz (post-quadrature)	
Commutation Startup:	Auto-phase - no Hall sensors required	
Connectors		
Auxiliary Feedback, I/O, Analog I/O:	Wire trap screw terminals	
Motor Feedback:	Wire trap screw terminals	
Serial Port:	9-pin D-sub	
Main AC, Motor Power and DC Bus:	Screw terminal block	
Approvals:	UL, CUL, CE	
Environmental		
Storage Temperature:	-40°C to 70°C (-40°F to 158°F)	
Operating Temperature:	0°C to 50°C (32°F to 126°F)	
Humidity:	5% to 95% noncondensing	

#### **APPLICATIONS FOR SW44 AND PV30**

The combination of the SW44 linear actuator and PV30 motor drive/controller/PLC creates a high performance package for many demanding applications. The zero maintenance and durability of the SW44 combined with the ease of use of the PV30 makes an excellent automation package.

#### Typical applications:

- Hydraulic cylinder replacement
- Stamping / pressing / embossing
- Precision valve control
- Volumetric pumps / filling
- Part clamping
- Packaging machinery
- Medical equipment
- Automation and assembly



## Axiom PV30 DIMENSIONS



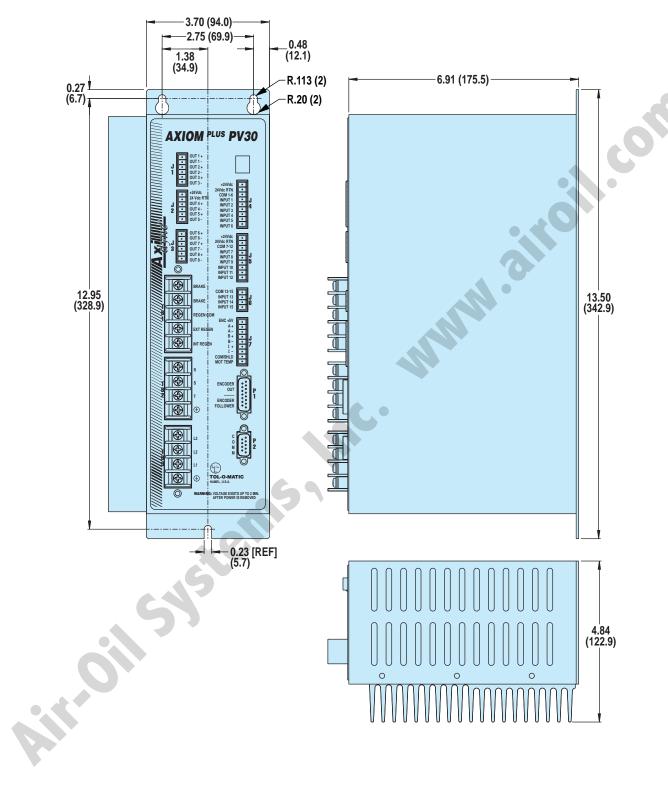


FEATURES SPECIFI-CATIONS

DIMENSIONS

PLC / SEQUENTIAL PROGRAM EDITORS

ORDERING



## PLC / SEQUENTIAL PROGRAM EDITORS



**MOIXA PV30** 

**FEATURES** 

SPECIFI-CATIONS

DIMENSIONS

SEOUENTIAL

**PROGRAM** 

**EDITORS** 

**ORDERING** 

PLC /



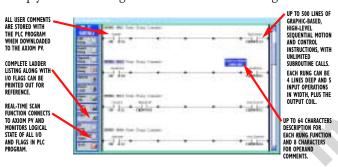
A configuration option for motor selection and related parameters is included, along with a tuning and diagnostic mode. Help menus and control loop description information can be accessed from the main menu.

The Axiom PV also includes a point and click sequential program and PLC ladder logic editor. Instructions include incremental and absolute motion commands, branching (conditional and unconditional), subroutine calls, repeat loops, I/O control, time delays, etc. Use the PLC editor to enter and edit PLC programs, which run using an independent scan. The PLC program accesses all 15 inputs and 8 outputs of the Axiom PV, including general purpose and dedicated internal

Both of these editors utilize easy icon/text driven selections, making the creation of motion profiles a snap (no code memorization required).

#### **AXIOM PV PLC EDITOR**

The PLC Editor main menu allows user access to all editing functions along with a 175 rung ladder display. Rungs can be inserted at any point in the program and are easily edited by simply double-clicking with the mouse and selecting the



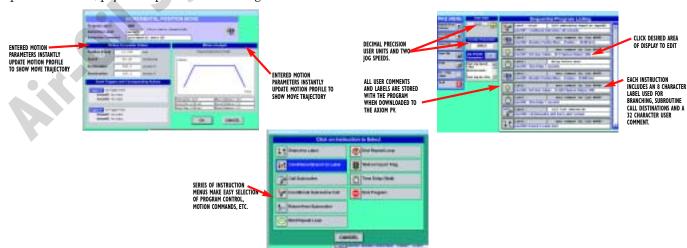
desired functions from subsequent menus. The PLC program's real-time scan is continuous upon power-up and ranges from 2-4 milliseconds for a typical application, with 10-12 milliseconds for a maximum-length program.



#### **AXIOM PV PLC SEQUENTIAL EDITOR**

The Sequential Editor main menu provides easy access to all essential program and display functions. Using a series of menus, the program guides the user through instruction selection. The Incremental Position Move window allows two separate trigger moves to be defined based on incremental position reached, physical input transition or flag from the

PLC. Two actions can be commanded for each trigger event including torque limit or velocity change, output control or flag passing to PLC. This functionality allows an almost limitless combination of functions associated with a single move, while the PLC facilitates real-time control.







AXIOM PV30

**FEATURES** 

SPECIFI-

**CATIONS** 

DIMENSIONS

SEQUENTIAL PROGRAM

EDITORS ORDERING

PLC /

## Axiom PV30

#### **ORDERING**

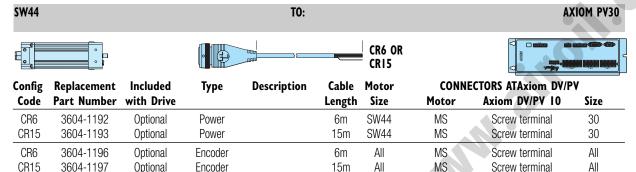


*AXIOM PV CONTROLLER / DRIVE				
Config.	Code	Includes	Part #	
PV30 Controller/Drive (order cables below)		3604-0010		

<sup>\*</sup>Includes user manual and software CD-ROM

#### **Cables**

#### SW44 TO AXIOM PV DRIVE/CONTROLLER



#### CONTROLLER TO IBM COMPATIBLE PC **AXIOM PV30** T0: PC CRZ Replacement Included Description Cable **CONNECTORS AT** PC Config Type Drive Part Number with SSC Code Length **Axiom PV** PC Size CRZ DB9 3600-1172 Optional Comm Žm AxiomPV DB9 ΑII

## BYTOL-O-MATIC



#### **TOL-O-MATIC, INC.**

3800 County Road 116 • Hamel, MN 55340 U.S.A. Phone: (763) 478-8000 • Fax: (763) 478-8080

Toll-Free: 1-800-328-2174

Email: help@tolomatic.com

URL: http://www.axidyne.com or http://www.tolomatic.com



All brand and product names are trademarks or registered trademarks of their respective owners. Information in this document is believed accurate at time of printing. However, ToI-O-Matic assumes no responsibility for its use or for any errors that may appear in this document. ToI-O-Matic reserves the right to change the design or operation of the equipment described herein and any associated motion products without notice. Information in this document is subject to change without notice.