





The IMA is a compact, durable, high force rod-style actuator. The IMA integrates a servo motor with a proven mechanical design to provide efficient high force in a compact lightweight design envelope. Our patent-pending design allows for easy re-lubrication without disassembly for extremely long service life.



#### Features:

- Compact, lightweight design
- Long life
- High force
- High positional accuracy
- High efficiency
- Proven performance
- Flexibility
- Compatibility
- Low inertia

#### Eliminates:

- Couplers
- Adapters
- Belts
- Gears
- Unneeded assembly labor
- Forced air or water cooling
- Hydraulic systems
- Pneumatic systems
- Need for multiple vendors

PATENT PENDING SCREW LUBRICATION SYSTEM





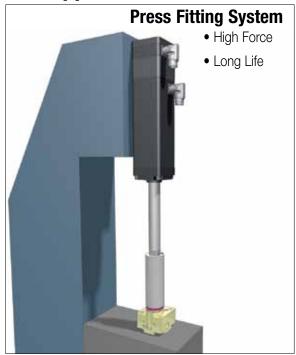
## Look For:

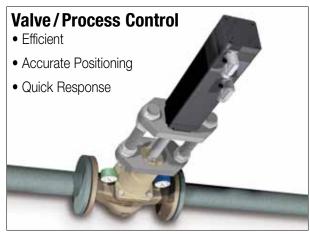
Endurance Technology features are designed for maximum durability to provide extended service life. This endurance technology symbol indicates our durability design features.

## **CONTENTS**

What is the IMA?2	IMA Specs & Performance 6-8	Selection Guidelines 14
IMA Applications 3	IMA Dimensions9-12	Ordering 15
IMA Features 4	Application Data Worksheet 13	

## **IMA Applications**









## **Other Applications:**

- Animation
- Assembly
- Automated assembly
- Automatic tool changers
- Automotive
- Clamping
- Converting
- Conveyors
- Cycle testing
- Fillers
- Formers

- Hydraulic replacement
- Laser positioning
- Machine tools
- Material handling systems
- Medical equipment
- Molding
- Motion simulators
- Open/close doors
- Packaging equipment
- Parts clamping
- Patient lifts

- Pick & place
- Pneumatic replacement
- Precision grinders
- Product test simulations
- Riveting / fastening / joining
- Robot manipulator arms
- Sawmill equipment
- Semiconductor
- Stage motion control

- Stamping
- Table positioning
- Tension control
- Test stands
- Tube bending
- Volumetric pumps
- Water jet control
- Wave generation
- Web guidance
- Welding
- Wire winding

# **IMA INTEGRATED MOTOR ACTUATOR**

Endurance Technology features are designed for maximum durability to provide extended service life.

## MULTIPLE SCREW TECHNOLOGIES YOU CAN CHOOSE:

- •Ball nuts offer positioning accuracy and repeatability
- •Roller nuts (coming soon) provide the highest thrust and life ratings available





## REPLACEABLE BEARING **CARTRIDGE**

•Doubles as a locating pilot for positioning actuator

 Prevents contaminants from entering the actuator for extended life

#### **ogrease Port ○**

- Patent pending screw relubrication system provides extended screw service life
- •Convenient lubrication without disassembly

## INTEGRAL MOUNTING

•Four threaded holes on front face are available for direct mounting or addition of customized options

- •Zinc plated alloy steel construction for
- Provides a common interface to multiple rod end options

- •Steel thrust tube supports extremely high force capabilities
- •Salt bath nitride treatment provides excellent corrosion resistance, surface hardness and is very resistant to adherence of weld slag, water and other potential contaminants

Bumpers protect the screw and nut assembly from damage at end of stroke

## 

- corrosion resistance

 Black anodized extrusion design is optimized for rigidity and strength

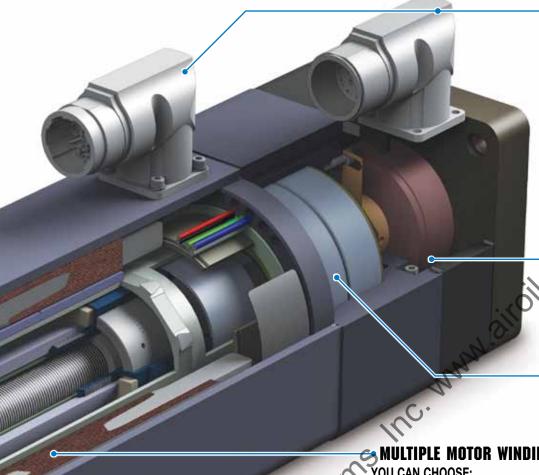
# IMA SPECIFICATIONS: pg. 6 SIZES **MAXIMUM**

STROKE: 18" THRUST: 2,000 lbf SPEED: 23 in/sec

COMPLETE INFORMATION: www.tolomatic.com

IMA 4





## **CONNECTORS** • YOU CAN CHOOSE FROM:

- Connector choice and wiring emulates popular motor manufacturers for compatibility:
- Tolomatic Standard
- -Bosch Rexroth MSK Series
- Emerson FM & NT Series
- Lenze MCA Series
- -more to come...
- STAGGERED CONNECTORS for more convenient installation
- 270° Rotatable & Box mount options available

## HIGH RESOLUTION. **FEEDBACK**

## YOU CAN CHOOSE:

- Digital encoder
- Multi-turn absolute encoder
- Resolver

## ⇒HIGH THRUST BEARING•

 Provides complete support of screw and protects the feedback device from linear forces

## 🗪 MULTIPLE MOTOR WINDINGS •

#### YOU CAN CHOOSE:

- •230V or 460V rated windings potted directly into actuator housing
- •Skewed motor windings pro vide minimal torque ripple for smooth linear motion
- •Integral thermal switch for over temperature protection

## HIGH POSITIONAL ACCURACY

ACCURACY

Roller Nut  $\pm 0.0004$ "/ft.  $\pm 0.0102$ mm/300mm Ball Nut  $\pm 0.002$ "/ft.  $\pm 0.051$ mm/300mm

 Eliminates potential contaminant collection points



#### **Modifications:**

 Contact Tolomatic for Stainless Steel, Food Grade or Mil-Spec versions of the IMA

## **OPTIONS**

## MOUNTING



• Side Mounting Holes, 2 sides & bottom (no photo)



• External Threads







• Front Flange • Trunnion, Rear or Front

water and dust ingress

### ROD END

• Internal Thread - Standard









 Spherical Eye Alignment Coupler **IP67** • For protection against

BRAKE

**CABLES** 



• 24V Spring held electronically released

• Signal Cable (6m)

• Power Cable (6m)

AR0

Anti-Rotate



IMA 5

#### **Performance & Mechanical Specifications:**

SERIES	IMA33 IMA44			<b>A44</b>		
	in	3.3		4.4		
SIZE	SIZE mm 83.0		110.0			
	in		6.0 to		· · · · · · · · · · · · · · · · · · ·	
STROKE	mm		152.4 t	o 457.2	7.2	
NUT/SCREW		BN05	BN10	BN05	BN10	
000514/1540	in	0.197	0.394	0.197	0.394	
SCREW LEAD	mm	5.0	10.0	5.0	10.0	
DYNAMIC	lbf	1709	1214	3395	3372	
(1 mil revs)	N	7602	5400	15100	15000	
, ,	in/ft		0.0	002		
LEAD ACCURACY	mm/300		0.0			
11000111101	in	0.004	0.004	0.005	0.005	
BACKLASH	mm	0.10	0.004	0.003	0.13	
CONT.	lbf	850	425	1650	825	
THRUST	N	3781	1891	7340	3670	
PEAK	lbf	1000	850	2000	1650	
THRUST	N	4448	3781	8896	7340	
MAX. VELOCITY	in/sec	11	22	11	22	
	mm/sec	279	559	279	559	
	°F	50 to 122				
TEMP RANGE	°C		10 t	to 50		
IP RATING	St	andard IP65, Optional IP67				
**BASE	lb	14.1 28.6				
WEIGHT	kg	6.4 13.0		3.0		
WEIGHT PER	lb/in.	0.6603 1.1035		035		
UNIT OF STROKE	kg/mm	0.0118 0.0197				
**BASE	• lb-in²	1.649	1.653	3.311	3.321	
INERTIA <sup>1</sup>	kg-cm <sup>2</sup>	4.826	4.837	9.689	9.719	
INERTIA PER UNIT OF STROKE	lb-in²/in	0.003	0.003	0.018	0.019	
	kg-cm <sup>2</sup> /mm	0.0003	0.0004	0.0021	0.0022	
BREAKAWAY	in-lb	2.4	2.3	4.3	3.6	
TORQUE	N-m	0.271	0.260	0.486	0.407	
BACK DRIVE	lbf	60	28	100	44	
FORCE*	N	267	126	445	196	

<sup>\*</sup>In vertical applications an unpowered IMA will require a brake to maintain position if the load on the actuator exceeds this value

## MAKE THE RIGHT CHOICE!

IMA 6

Tolomatic's sizing software is a great tool to help choose the right IMA. OR Contact Tolomatic for assistance in choosing the correct IMA actuator and options required for your application.

#### **Motor Specifications:**

	SERIES		<b>A33</b>	IMA44	
	/OLTAGE	MV23	MV43	MV23	MV43
TORQUE	in-lb/A Peak	5.5	10.7	5.4	10.6
CONSTANT (K <sub>t</sub> )	N-m/A Peak	0.62	1.21	0.61	1.20
VOLTAGE CONSTANT (K <sub>e</sub> )	V/Krpm Peak	79.8	154	78.1	153.1
CONTINUOUS	in-lb	35	34	67	67
STALL TORQUE	N-m	4.0	3.8	7.6	7.6
CONTINUOUS STALL CURRENT	Arms	4.5	2.25	8.8	4.5
PEAK TOROUE	in-lb	70 68 13		34	
PEAK TURQUE	N-m	7.9	7.7	15.2	
PEAK CURRENT	Arms	9	4.5	17.6	9.0
RESISTANCE	Ohms	2.07	8.3	0.58	2.32
INDUCTANCE	mH	3.8	15	2.75	11.5
NO. OF POLES		8			
BUS VOLTAGE	Vrms	230	460	230	460
SPEED @ Rated v	RPM	3500			

RoHs Compliant Components, U\_L (€ Approval Pending

NOTE: Both IMA33 and IMA44 actuators were characterized using an aluminum face mount plate (8.25" x 7.0" x 0.7")

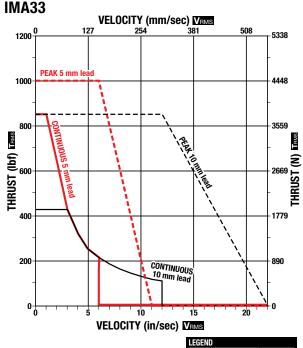
**Brake Specifications:** 

	SERIES	IMA33	IMA44
ROTOR	oz-in <sup>2</sup>	0.112	0.656
INERTIA	gm-cm <sup>2</sup>	20.5	120.0
CURRENT	Amp	0.516	0.67
HOLDING	in-lb	35	80
TORQUE	N-m	4.0	9.0
ENGAGE TIME	mSec	20	50
DISENGAGE TIME	mSec	70	40
VOLTAGE	Vdc	24	24

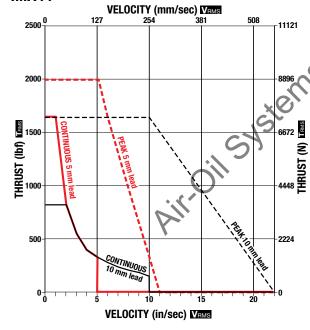


<sup>\*\*</sup>Value given is for a zero stroke actuator

## SPEED vs THRUST



#### IMA44



# CALCULATING RMS THRUST AND VELOCITY

Servo motor actuator systems have two speed/thrust curves: one for continuous duty operation and another for intermittent (peak) duty. A servo system can be selected according to the total thrust and maximum velocity indicated by the continuous duty curve. However, by calculating the root mean square (RMS) thrust based on the application duty cycle, you may be able to take advantage of the higher peak thrust available in the intermittent duty range. The RMS thrust must fall within the continuous duty region of the motor/drive and the application maximum thrust must fall under the peak thrust of the actuator. Use the following formulae when calculating the RMS thrust and velocity. When selecting an integrated servo actuator system, it is necessary to add a margin of safety to the thrust and velocity required to move the load. The recommended margin for servo motors is 15%.

$$\mathbf{T}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{T}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}}$$

$$\mathbf{V}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{V}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}}$$

Where

CONTINUOUS

 $\mathbf{T}_{\text{RMS}} = \text{RMS Thrust}$ 

**V**<sub>RMS</sub> **S** RMS Velocity

 $\mathbf{T}_{i} = \text{Thrust during interval i}$ 

**V**; = Velocity during interval i

 $\mathbf{t}_{_{\mathrm{i}}} = \text{Time interval i}$ 

## **BRAKE CONSIDERATIONS**

An unpowered IMA will require a brake to maintain its position if the force on the actuator exceeds Back Drive Force listed in the table on page 6.

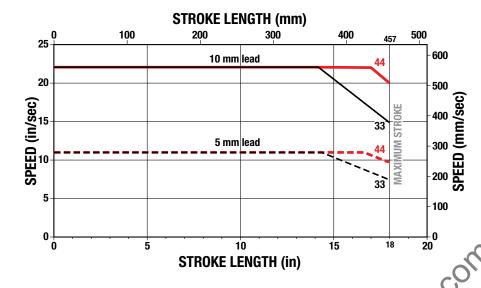
A brake can be used with the actuator to keep it from back-driving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold position when unpowered. See page 15 for ordering information.

NOTE: The optional Spring-Applied/Electronically-Released Brake requires 24V power. Input current rating: IMA33 - 0.516 Amps; IMA44 - 0.67 Amps.

#### QUESTIONS?

Contact Tolomatic for assistance in choosing the correct IMA actuator and options required for your application.

## CRITICAL SPEED



NOTE: The L<sub>10</sub> expected life of a ball screw linear actuator is expressed as the linear travel distance that 90% of properly maintained ball screws manufactured are expected to meet or exceed. This is not a guarantee and this graph should be used for estimation purposes only.

The underlying formula that defines this value is:

$$\mathbf{L}_{10} = \left( \begin{array}{c} \mathbf{C} \\ \mathbf{F} \end{array} \right)^3 \equiv$$

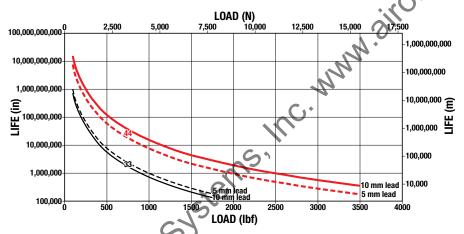
Travel life in millions of inches, where:

> **C** = Dynamic load rating (lbf)

> $\dot{\mathbf{F}}$  = Cubic mean applied load (lbf)

All curves represent properly lubricated and maintained actuators.





## SIDE LOAD CONSIDERATIONS

The IMA integrated motor actuator is not meant to be used in applications where side loading occurs.

Loads must be guided and supported. Loads should be aligned with the line of motion of the thrust rod.

Side loading will affect the life of the actuator.

## FREE - Windows® compatible software. download at www.tolomatic.com Or Call 1-800-328-2174 for **Excellent Customer Service & Technical Support**

## **LUBRICATION:** DO NOT FILL WITH GREASE!

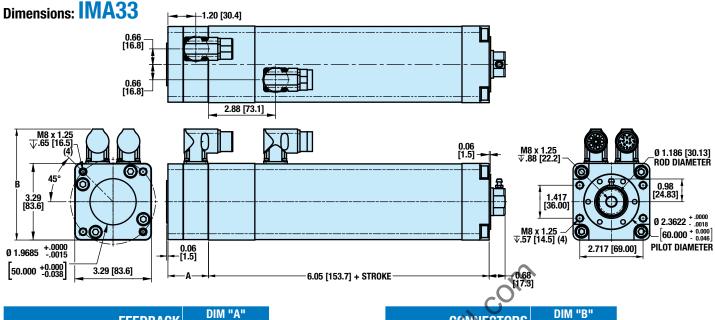
IMA actuators have been lubricated at the factory and are ready for installation. For many applications the unit is greased for life.

- For light to moderate use, no additional lubrication is required.
- For severe duty use, periodic re-lubrication will be necessary to maintain optimum performance. Grease should be added every 1,000 hours of operation.
- Re-lubricate with Mobilith SHC220 (IMA33: 3.0 g; IMA44 5.0 g) in the grease zerk provided.

Overfilling will cause a reduction in performance, excessive heat build up and potential premature failure.

#### **QUESTIONS?**

Contact Tolomatic for assistance in choosing the correct IMA actuator and options required for your application.



FEEDBACK	DIM	"A"
FEEDDAGK	in	mm
Digital Encoder	1.74	44.2
Digital Encoder with Brake	3.18	80.8
Digital Encoder (Emerson NT)	1.98	50.3
Digital Encoder with Brake (Emerson NT)	3.68	93.5
Resolver	1.74	44.2
Resolver with Brake	3.18	80.8
Absolute Encoder	TBD*	TBD*
Absolute Encoder w/ Brake	TBD*	TBD*

\*TBD = To Be Determined

CONNECTORS

in mm

folomatic Standard
Bosch MSK Motor Series
Emerson FM Series
Lenze MCS Motor Series
Emerson NT Series\*\*

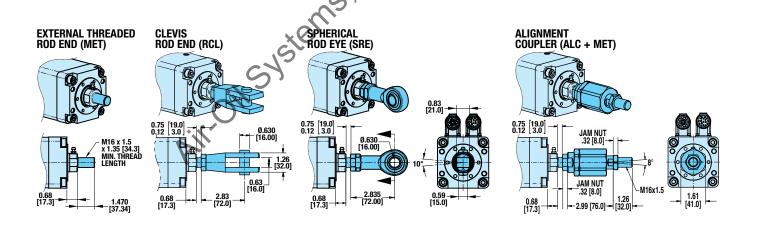
4.81

122.2

\*\*Uses Box Mount Connectors (IP67 not available)

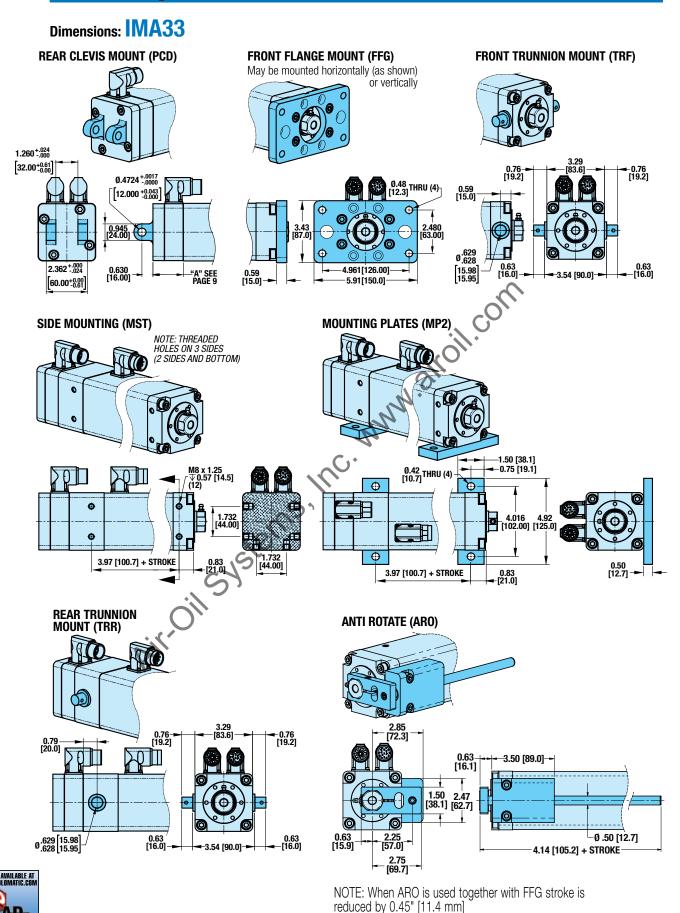
IMA 9

\*\*Uses Box Mount Connectors (IP67 not available



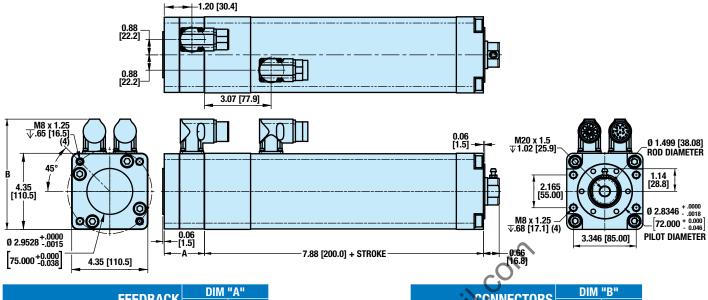


- Go to www.tolomatic.com
- Click on this icon
- · Configure stroke length and download
- Place the solid model in your application assembly



2D

## Dimensions: IMA44

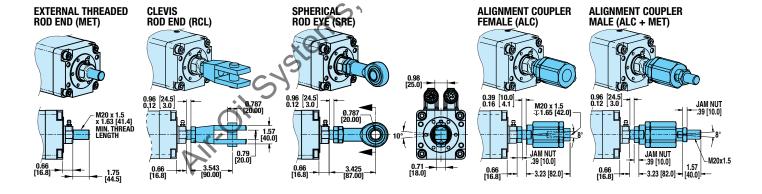


FEEDBACK	DIM "A"	
FEEDDAGK	in	mm
Digital Encoder	1.74	44.2
Digital Encoder with Brake	3.15	80.0
Digital Encoder (Emerson NT)	1.98	50.3
Digital Encoder with Brake (Emerson NT)	3.50	89.0
Resolver	1.74	44.2
Resolver with Brake	3.15	80.0
Absolute Encoder	TBD	TBD
Absolute Encoder with Brake	TBD	TBD

\*TBD = To Be Determined

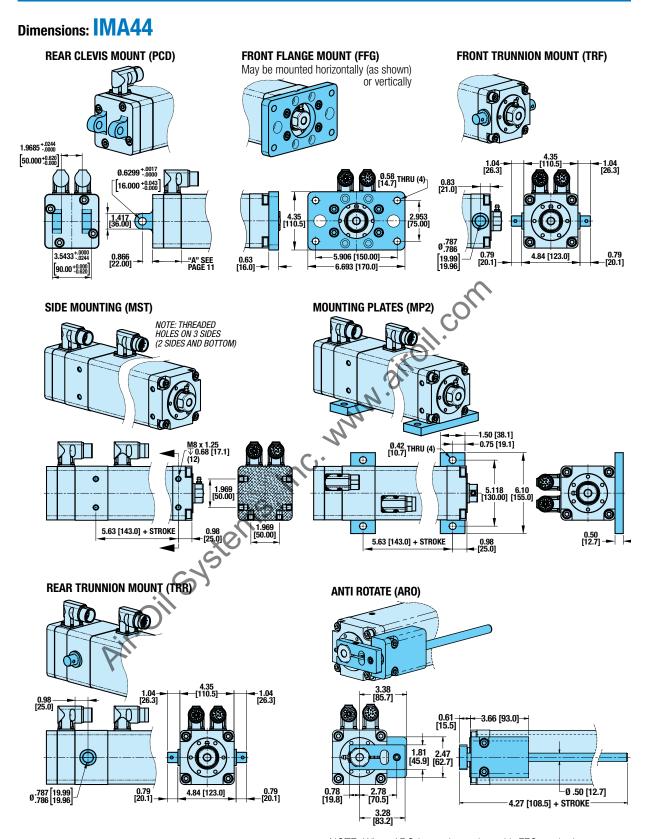
| CONNECTORS | DIM "B" | in | mm | Tolomatic Standard | Emerson FM Series | 5.89 | 149.6 | Enze MCS Motor Series | 5.89 | 149.6 | Emerson NT Series\*\* | 5.50 | 139.7 |

\*\*Uses Box Mount Connectors (IP67 not available)





- Go to www.tolomatic.com
- Click on this icon
- · Configure stroke length and download
- Place the solid model in your application assembly







# APPLICATION DATA WORKSHEET Fill in known data. Not all information is required for all applications ORIENTATION Uvertical Incline of a linchine of a linch

☐ Load supported by actuator OR ☐ Load supported by other mechanism



MOVE PROFILE		iTH		
EXTEND	inch (SK) (U.S. Standard)	☐ millimeters (SM) (Metric)	Repeatability	   millimeters
Move Distance				
☐ inch ☐ millimeters	NOTE: If load or	force changes during cycle numbers for calculations	OPERATING ENV	/IRONMENT
Move Timesec	O .	numbers for calculations	Temperature, Conta	amination, etc.
Max. Speed mm/sec	EXTEND	RETRACT		
	LOAD	LOADka	. 60	
Dwell Time After Movesec				
RETRACT	(U.S. Standard) (Met	ric) (U.S. Standard) (Metric)	110	
Move Distance	FORCE	FORCE	9.,	
inch millimeters		kg. □ lb. □ kg.	•	
Move Timesec		ric) (U.S. Standard) (Metric)		
Max. Speed		n		
☐ in/sec ☐ mm/sec	MOTION DDOE	u = -C)*		
Dwell Time After Movesec	MOTION PROF	ILE		Graph your most
	+ Speed ( )			demanding cycle,
NO. OF CYCLES		2,		including accel/decel
☐ per minute ☐ per hour				times. You may also want to indicate load
				variations and I/O changes during the
<b>HOLD POSITION?</b> Required				cycle. Label axes with proper scale and
☐ Not Required				units.
☐ After Move ☐ During Power Loss				
			Time or Distance	( )-
Y				
	-			
CONTACT INFORMATION Name, Phone, Email Co. Name, Etc.				

STOP

**USE THE TOLOMATIC SIZING AND SELECTION SOFTWARE AVAILABLE ON-LINE AT www.tolomatic.com OR... CALL TOLOMATIC AT 1-800-328-2174.** We will provide any assistance needed to determine the proper actuator for the job.

FAX 1-763-478-8080

**EMAIL help@tolomatic.com** 

## Selection Guidelines

ESTABLISH MOTION PROFILE

Using the application stroke length, desired cycle time and loads establish the motion profile details.

the actuator's body can approach 180°F (82°C) in aggressive applications. Adequate clearance to ensure actuator's ambient conditions do not rise drastically should be allowed.

COMPARE PEAK THRUST AND SPEED TO PEAK CAPACITIES

Calculate the application required peak thrust and speed and compare to graphs on page 7. (repeated below) Select an actuator that achieves the necessary peak thrust and speed.

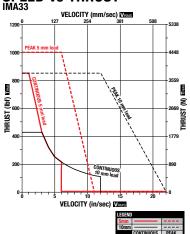
BRAKE CONSIDERATIONS

An unpowered IMA will require a brake to maintain its position if the force on the actuator exceeds Back Drive Force listed in the table on page 6.

A brake can be used with the actuator to keep it from back-driving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold position when unpowered. See page 15 for ordering information.

NOTE: The optional Spring-Applied/Electronically-Released Brake requires 24V power. Input current rating: IMA33 - 0.516 Amps; IMA44 - 0.67 Amps.

SPEED vs THRUST



CHOOSE MOTOR CONNECTORS & FEEDBACK DEVICE

Connector choice and wiring emulates popular motor manufacturers for compatibility.

Current connector choices include:

• Rosch Reyroth MSK Series

Bosch Rexroth MSK Series

Emerson FM & NT Series

Lenze MCA Series

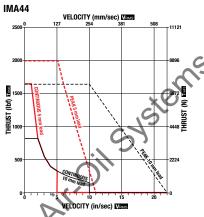
Current feedback choices include:

• Digital Encoder

Absolute Encoder

Resolver

Contact Tolomatic for additional motor connectors and feedback combinations



COMPARE CONTINUOUS THRUST AND SPEED TO CONTINUOUS CAPACITIES

Calculate the Continuous or RMS thrust and speed required and compare to graphs on page 7. (repeated above) Select an actuator that achieves the necessary thrust and speed for continuous operation. See complete instructions on page 7 for help calculating continuous force.

$$\mathbf{T}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{T}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}} \quad \mathbf{V}_{\text{RMS}} = \sqrt{\frac{\text{sum } (\mathbf{V}_{i}^{2} \times \mathbf{t}_{i})}{\text{sum } (\mathbf{t}_{i})}}$$

**T**CONSIDER MOUNTING & ROD END OPTIONS

Examine mounting options dimensional drawings on page 9 to 12. Standard mounting on the IMA are 4 tapped holes on the front rod end face of the actuator. The Side Mount option (MST) includes 12 tapped holes, 4 on each side and 4 on the bottom of the actuator. Other fixed mounting options are the Front Flange Mount (FFG) and Mounting Plates (MP2). Pivoting mount options are Front Trunnion (TRF), Rear Trunnion (TRR) and Rear Clevis Mount (PCD).

Rod End Options include: External Threaded Rod End (MET), Clevis Rod End (RCL), Spherical Rod Eye (SRE) and Alignment Coupler (ALC).

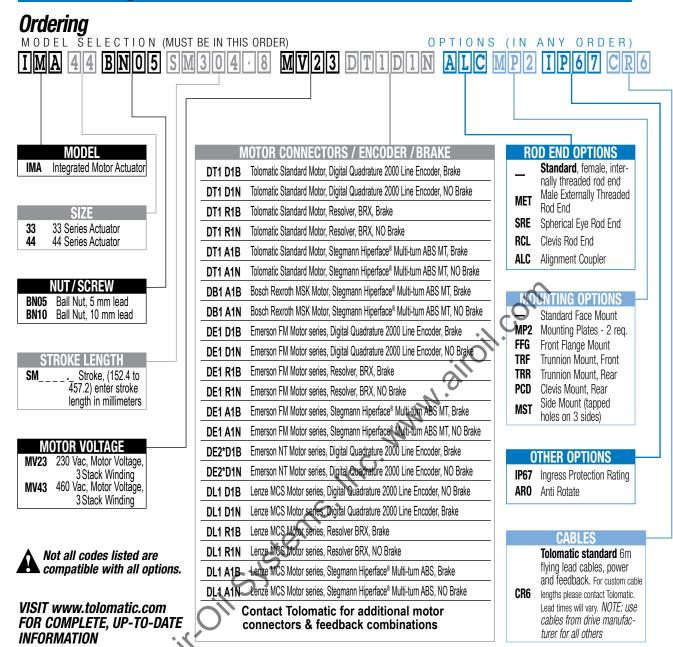
NOTE: Regardless of the mounting option chosen, care must be taken to ensure that the load is guided and in-line with the thrust rod's line of motion. Misalignment of the thrust rod's line of motion will cause degradation in the actuator's expected life.

**TEMPERATURE** 

The IMA is intended to operate in an environment with an ambient temperature between 50-122° F, (10-50° C). Performance should be de-rated if the ambient temperature is above 77° F (25° C). Contact the factory if the ambient temperature does not fit within this range. NOTE: Temperature of

# CONSIDER ENVIRONMENTAL RATING AND ANTI-ROTATE OPTIONS

The environmental rating for a standard IMA is IP65, choose IP67 for protection against water and dust ingress. Choose the Anti-Rotate Option (ARO) if required. Call Tolomatic at 1-800-328-2174 for help in determining the best actuator for your application.



\*NOTE: IP67 is not available with DE2 (Emerson NT connectors)

Call Tolomatic 1-800-328-2174 to determine available options and accessories based on your application requirements.

## Replacement Option Parts Ordering

	mont opaion i and ordering
PART NO.	DESCRIPTION
2733-9014	Spherical Rod Eye Kit, IMA33
2744-9014	Spherical Rod Eye Kit, IMA44
2733-9015	Clevis Rod End Kit, IMA33
2744-9015	Clevis Rod End Kit, IMA44
2132-1060	Alignment Coupler Kit, IMA33
2150-1060	Alignment Coupler Kit, IMA44
2733-9010	Mounting Plate Kit, IMA33
2744-9010	Mounting Plate Kit, IMA44
2733-9018	Front Flange Mount Kit, IMA33
2744-9018	Front Flange Mount Kit, IMA44
2733-1045	Rear Clevis Mount, IMA33
2744-1045	Rear Clevis Mount, IMA44
2733-9075	Anti Rotate, Bearing Assy, IMA33 & IMA 44

PART NO.	DESCRIPTION
2733-9074	Anti Rotate, Shaft Clamp, IMA33
2733-1211	Anti Rotate, Shaft, IMA33 - Indicate Stroke
2744-9074	Anti Rotate, Shaft Clamp, IMA44
2744-1211	Anti Rotate, Shaft, IMA44 - Indicate Stroke
2733-1221	Motor Power Cable, IMA33 NO Brake
2733-1222	Motor Power Cable, IMA33 with Brake
2744-1221	Motor Power Cable, IMA44 NO Brake
2744-1222	Motor Power Cable, IMA44 with Brake
2733-1223	Feedback Cable, 12 pin (Resolver & Stegmann)
2733-1224	Feedback Cable, 17 pin (Digital Encoder)

All parts are listed for REPLACEMENT ONLY. If not ordered on original unit the IMA may require additional tapped holes or replacement rod end. Contact Tolomatic.

## THE TOLOMATIC DIFFERENCE What you expect from the industry leader:



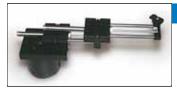
## **EXCELLENT CUSTOMER SERVICE & TECHNICAL SUPPORT**

Our people make the difference! Expect prompt, courteous replies to all of your application and product questions.



## **INDUSTRY LEADING DELIVERIES**

Standard catalog products are built to order and ready-to-ship in 5 days or less. Modified and custom products ship weeks ahead of the competition.



## **INNOVATIVE PRODUCTS**

From standard catalog products... to modified products... to completely unique custom products, Tolomatic designs and builds the best solutions for your challenging applications.



## **SIZING & SELECTION SOFTWARE**

Windows® compatible, downloadable from our website FREE – the best tool of its kind on the market! Product selection has never been easier.



## 3D MODELS & 2D DRAWINGS AVAILABLE ON THE WEB

Easy to access CAD files are available in many popular formats.

## ALSO CONSIDER THESE OTHER TOLOMATIC PRODUCTS:

#### PNEUMATIC PRODUCTS



RODLESS CYLINDERS: Band Cylinders, Cable Cylinders, MAGNETICALLY COUPLED CYLINDERS/SLIDES; GUIDED ROD CYLINDER SLIDES; ROTARY ACTUATORS
"FOLDOUT" BROCHURE #9900-9075 PRODUCTS BROCHURE #9900-4028 www.tolomatic.com/pneumatic

#### **ELECTRIC PRODUCTS**



ROD & GUIDED ROD STYLE ACTUATORS, HIGH THRUST ACTUATORS, SCREW & BELT DRIVE RODLESS ACTUATORS, MOTORS, AXIOM DRIVES/CONTROLLERS
"FOLDOUT" BROCHURE #9900-9074 PRODUCTS BROCHURE #9900-4016 www.tolomatic.com/electric

### POWER TRANSMISSION PRODUCTS



GEARBOXES: Float-A-Shaft®, Slide-Rite®; DISC CONE CLUTCH; CALIPER DISC BRAKE
"FOLDOUT" BROCHURE #9900-9076 PRODUCTS BROCHURE #9900-4029 www.tolomatic.com/pt



3800 County Road 116 • Hamel, MN 55340 U.S.A. Toll-Free: 1-800-328-2174

All brand and product names are trademarks or registered trademarks of their respective owners. Information in this document is believed accurate at time of printing. However, Tolomatic assumes no responsibility for its use or for any errors that may appear in this document. Tolomatic reserves the right to change the design or operation of the equipment described herein and any associated motion products without notice. Information in this document is subject to change without notice.

Visit www.tolomatic.com for the most up-to-date technical information

