

# numatics



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The **R Series** is a heavy-duty rack and pinion style rotary actuator that is designed to excel in the most rigid applications. The R Series includes a high torque-to-size ratio as well as accurate positioning.

#### **Rack and Pinion**

The **rack** and **pinion** is made from high strength alloy steel. It is induction hardened for long life. The geometry factors of the rack and pinion have been balanced to ensure equal wear, which provides maximum gear life. The pinion shaft includes a male key as standard offering.

#### **Ball Bearings**

The **ball bearings** are sealed and pre-lubed in an effort to prevent contamination from negatively affecting the operation. They are sized to except high loads and still retain smooth maintenance free operation.

#### **Rack Bushing**

The **rack bushing** is made from bearing bronze. The durability of the bushing enables it to support nearly the full length of the rack. Furthermore, we

have included a small gap to allow grease/lubrication to be added.

#### Tube

The profile **tube** is hard coat anodized. The hard coating is an electrochemical process, which produces a very dense surface of aluminum oxide. This surface has extreme hardness (60 RC.), excellent wear and corrosion resistance, and low coefficient of friction.

#### **End Caps**

The **end caps** are accurately machined from (6061-T6) solid aluminum bar stock. They are anodized for corrosion resistance. Additionally, port positioning is extremely flexible.

#### **Piston**

The solid aluminum alloy **piston** is strong and durable. A magnet groove is standard allowing for easy field conversation.

#### **Piston Seal**

The **piston seal** is a carboxilated intrile with Teflon® compound for self-lubricating. The U-cup type seal construction is proven and durable.

#### **Wear Band**

The **wear band** is a stable, lubricating strip located on the piston.

#### **Grease Opening**

A 1/4-28 tapped hole (which is plugged) is provided for future installation of an optional grease fitting. Note that the unit is pre-lubed.

Teflon® is a registered trademark of  $DuPont^{TM}$ . For detailed information regarding the properties of Teflon®.



#### **Standard Specifications:**

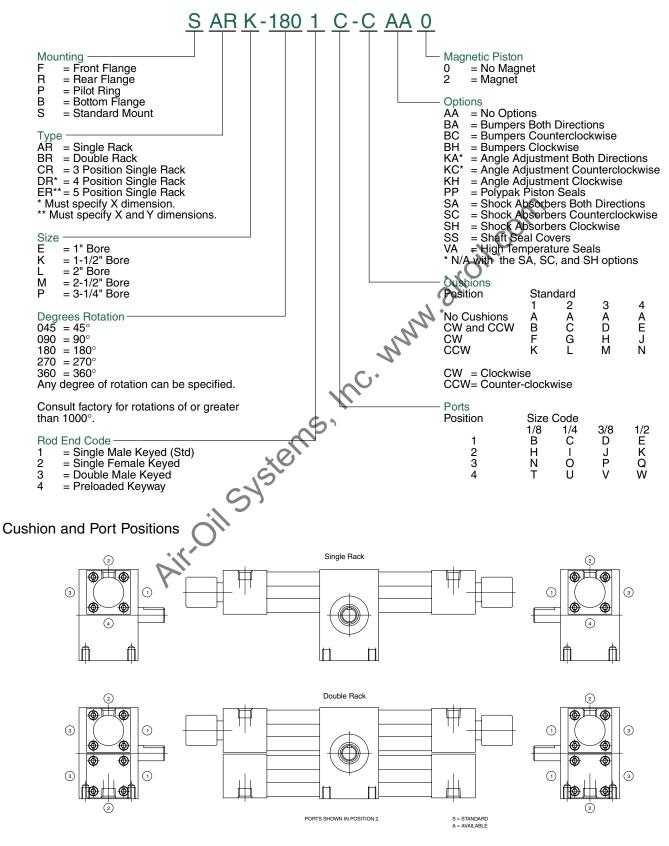
- Bore sizes from 1" through 3-1/4"
- Nominal pressure rating is 150 psi air
- Standard rotations are: 45°, 90°, 180°, 270°, and 360°
- Minimum breakaway pressure: 5 psi non-cushioned,
- 10 psi cushioned
- Standard temperature -10°F to 165°F (-23°C to 74°C)
- NPTF ports
- Flexible port locating

The keyway at position 12:00, is always the mid-rotation of the actuator unless otherwise specified.





# How to Order



NOTE: Consult factory for repair kit information.





Standard Specifications

Maximum operating pressure: 150 psi pneumatic

Standard rotations: 45°, 90°, 180°, 270°, 360° and other rotations optional

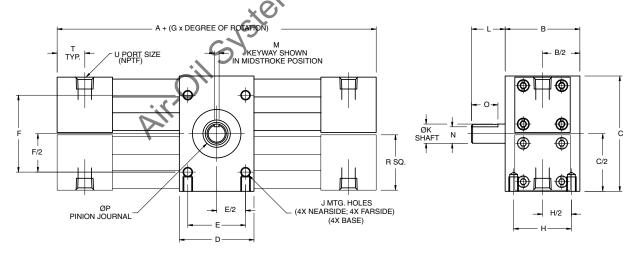
Maximum breakaway pressure: 5 psi non-cushion, 10 psi cushioned

Operating temperature: 0° F to 180° F (standard seals)
-20° F to 400° F (viton seals)

BORE	NUMBER OF	MODEL	THEORETIC			"MAX. ANGULAR BACKLASH,	MAX. ROTATIONAL		
BONE	RACKS	MODEL	50 psi	100 psi	150 psi	ROTATION	MINUTES"	TOTAL (DEGREES)	
1"	1	SARE	19	39	59	0.007	50	10	
1"	2	SBRE	39	79	118	0.014	50	10	
1 1/2"	1	SARK	59	118	177	0.021	40	8	
1 1/2"	2	SBRK	118	236	353	0.042	40	8	
2"	1	SARL	141	282	424	0.049	30	6	
2"	2	SBRL	282	565	848	0.099	30	6	
2 1/2"	1	SARM	276	552	828	0.096	30	6	
2 1/2"	2	SBRM	552	1104	1656	0.193	30	6	
3 1/4"	1	SARP	570	1141	1711	0.199	15	4	
3 1/4"	2	SBRP	1141	2281	3422	0.398	15	4	

Allow 10% for friction loss.





## **Dimensions**

BORE	Α	В	С	D	Е	F	G	Н	J	K	L	М	N	0	Р	R	Ţ	U	V
1"	7.50	2.00	3.00	2.00	1.50	2.00	0.01746	1.50	1/4-20 X 3/8 DEEP	.500/.499	0.88	.125/.127	.430/.425	.625	0.59	1.44	0.75	1/8	0.75
1-1/2"	8.50	3.00	4.25	3.00	2.00	3.00	0.02328	2.00	5/16-18 X 1/2 DEEP	.875/.874	1.88	.188/.190	.771/.761	1.50	0.98	2.00	0.75	1/4	1.13
2"	9.50	3.00	5.00	4.00	2.50	3.50	0.03124	2.00	3/8-16 X 1/2 DEEP	1.125/1.124	1.88	.250/.252	.986/.976	1.50	1.18	2.44	0.75	1/4	1.25
2-1/2"	9.75	3.50	6.00	4.00	2.50	4.50	0.03926	2.00	1/2-13 X 3/4 DEEP	1.375/1.374	2.25	.313/.315	1.201/1.191	1.75	1.57	2.94	0.75	1/4	1.50
3-1/4"	11.25	5.00	8.00	5.00	3.00	5.00	0.04800	2.50	3/4-10 X 1 DEEP	1.750/1.749	3.50	.375/.377	1.542/1.532	3.00	1.77	3.75	0.88	3/8	1.94

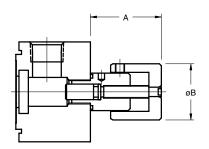




# **Options**

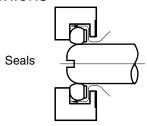
# **Rotation Adjust**

Rotation adjusting knobs can be added to control rotation more precisely. They can be used on both ends or on either end individually. Rotation adjusters can be used in conjunction with cushions. Their "high tech" style makes rotation adjustment easy to do without tools. The metric set screw in the side of knob securely locks the rotation setting. Thus, the rotation is very easy to adjust, but cannot be changed without a metric allen wrench. When used with cushions, maximum rotation adjustment will still allow at least 20° of rotation to be in cushion.



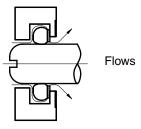
BORE	Α	В	DEGREE OF ROTATION PER END
1"	1.43	1.13	43
1 1/2"	1.43	1.13	32
2"	2.22	1.75	40
2 1/2"	2.22	1.75	32
3 1/4"	2.67	2.35	32

# Cushions



Into Cushion

Our cushion seal has a built-in function. It seals in one direction and permits full flow in the opposite direction.

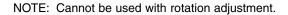


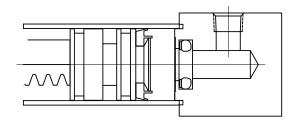
Out of Cushion

Cushions can be added to meter deceleration. Cushion adjustment needles can be put in any quadrant. Normally, cushions will be added to only one half of the double rack unit. The cushion and its operation is very similar to our current A series design. Rotation adjust can be used in conjunction with cushions. Cushions and Shock absorbers logether are not available.

# Bumpers

Bumper seals can be added to reduce impact. The bumper and seal are one piece. Bumpers can be used in conjunction with cushions if necessary.

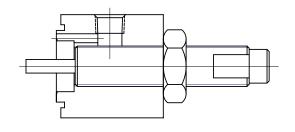




# **Shock Absorbers**

Hydraulic shock absorbers can be added to reduce noise and large impacts. Shocks are fixed orifice self-compensating type. The 3 1/4" bore rotary actuator will not have this option. Cushions and shock absorbers together are not available.

NOTE: Shock cannot be adjusted.

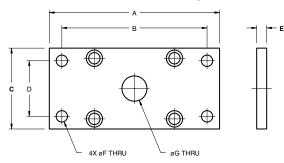






# **Mounting Options** Flanges

# Front and Rear Flange

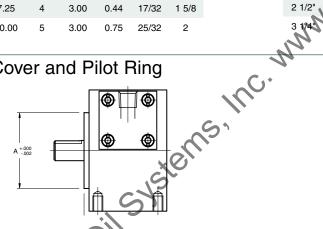


BORE	Α	В	С	D	Ε	F	G
1"	4.25	3.63	2	1.38	0.25	9/32	5/8
1 1/2"	5.75	5.13	3	2.13	0.44	13/32	1
2"	6.50	5.88	4	3.38	0.44	13/32	1 1/4
2 1/2"	8.25	7.25	4	3.00	0.44	17/32	1 5/8
3 1/4"	12.00	10.00	5	3.00	0.75	25/32	2

# **Bottom Flange**

BORE	Α	В	С	D	Е	F
1"	3.25	2.63	2	1.38	0.25	9/32
1 1/2"	4.50	3.88	3	2.13	0.44	13/32
2"	4.50	3.88	4	3.38	0.44	13/32
2 1/2"	5.50	4.50	4	3.00	0.44	17/32
3 1/4"	8.00	6.50	5	3.50	0.75	25/32

# Shaft Seal Cover and Pilot Ring

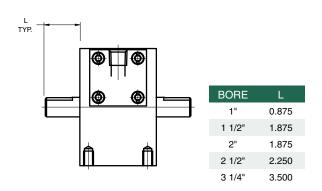


BORE	А	В
1"	1.875	0.125
1 1/2"	3.000	0.250
2"	3.250	0.250
2 1/2"	3.625	0.250
3 1/4"	4.480	0.250

The pilot ring and the shaft seal cover are dimensionally the same. Pilot rings are used to help center the shaft to the work piece. Shaft seal covers are used to prevent contamination to the ball bearings. They can only be used on single and double male shafts.

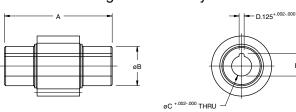
# **Shaft Options**

# Double Male Keyed



BORE	Α	В	С	D	Е
1"	1.81	0.59	0.250	N/A	N/A
1 1/2"	2.69	0.98	0.500	0.125	0.560
2"	2.72	1.18	0.688	0.187	0.780
2 1/2"	3.13	1.57	0.813	0.250	0.901
3 1//"	4 56	1 77	1 125	0.250	1 2/17

## Single Female Keyed







# Kinetic Energy Basic Formula

 $KE = 1/2 J\omega^2$ 

 $\omega$  = 0.035 x Angle traveled (degrees) Rotation time (seconds) Where:

KE = Kinetic Energy (in-lb)

J = Rotational mass moment of

inertia (in-lb-sec2)

(Dependent on physical size of

object and weight)

 $\omega$  = Peak Velocity (rad/sec)

(Assuming twice average velocity)

W = Weight of load (lb)

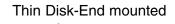
g = Gravitational constant = 386.4 in/sec<sup>2</sup>

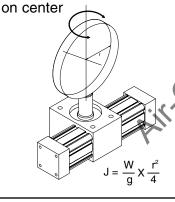
r = Radius of gyration (in)

# Moments of Inertia

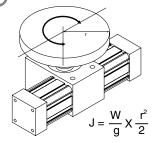
Maximum Kinetic Energy Rating for Models Based on Configuration (in-lb)

BORE	STANDARD	ROTATION ADJUSTERS	CUSHIONS	SHOCK ABSORBERS (PER CYCLE/PER HOUR)
1"	0.50	0.50	5	150/300,000
1 1/2"	2.00	2.00	20	225/400,000
2"	4.00	4.00	40	600/600,000
2 1/2"	7.00	7.00	70	600/600,000
3 1/4"	15.00	15.00	150	N/A

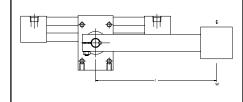




# Thin Disk Mounted on center

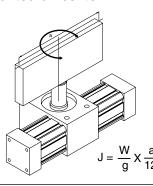


# Point Load

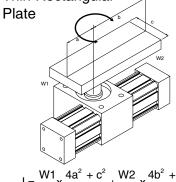


$$J = \frac{w}{g} x r^2$$

# Thin Rectangular Plate-Mounted on center

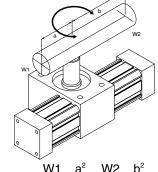


# Thin Rectangular



$$J = \frac{W1}{g} x \frac{4a^2 + c^2}{12} + \frac{W2}{g} x \frac{4b^2 + c^2}{12}$$

# Slender Rod



$$J = \frac{W1}{g}x\frac{a^2}{3} + \frac{W2}{g}x\frac{b^2}{3}$$



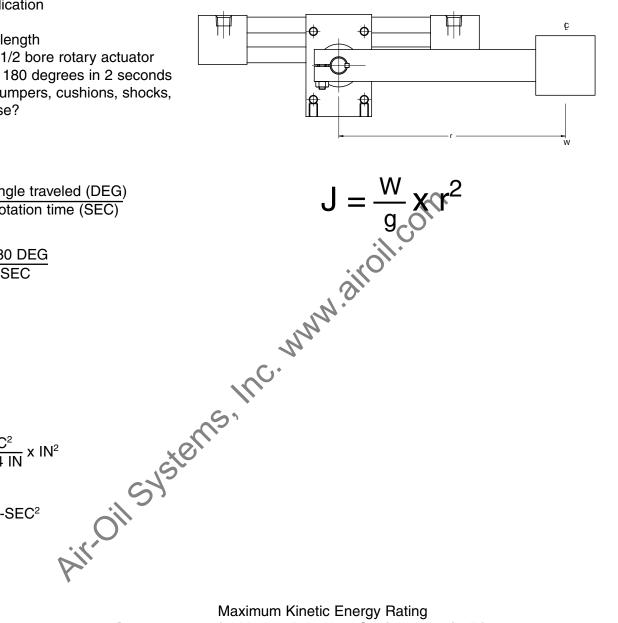


Size and Selection Example

Point load application W=5 lb. load r=12 inch arm length Want to use 1 1/2 bore rotary actuator Need to rotate 180 degrees in 2 seconds Should I use bumpers, cushions, shocks, or none of these?



Point Load



From Catalog:

$$\omega = 0.035 \text{ x}$$
 Angle traveled (DEG)
Rotation time (SEC)

$$\omega = 0.035 \times \frac{180 \text{ DEG}}{2 \text{ SEC}}$$

$$\omega = \frac{3.15}{\text{SEC}}$$

$$J = \frac{W}{q} \times r^2$$

$$J = 5 LB \frac{SEC^2}{386.4 IN} \times IN^2$$

$$J = 1.86 \text{ IN-LB-SEC}^2$$

$$KE = 1/2 J\omega^2$$

$$KE = \frac{1}{2} \times 1.86 \text{ IN-LB-SEC}^2 \times \left(\frac{3.15}{\text{SEC}}\right)^2$$

Looking at Kinetic Energy Rating Chart:

Maximum Kinetic Energy Rating for Models Based on Configuration (in-lb)

BORE	STANDARD	STROKE ADJUSTERS	CUSHIONS	SHOCK ABSORBERS (PER CYCLE/PER HR.)
1"	0.50	0.50	5	150/300,000
1 1/2"	2.00	2.00	20	225/400,000
2"	4.00	4.00	40	600/600,000
2 1/2"	7.00	7.00	70	600/600,000
3 1/4"	15.00	15.00	150	N/A

Maximum KE=20 IN-LBS for a 1 1/2" bore rotary with cushions

Therefore, application requires cushions.





# **Specifications**

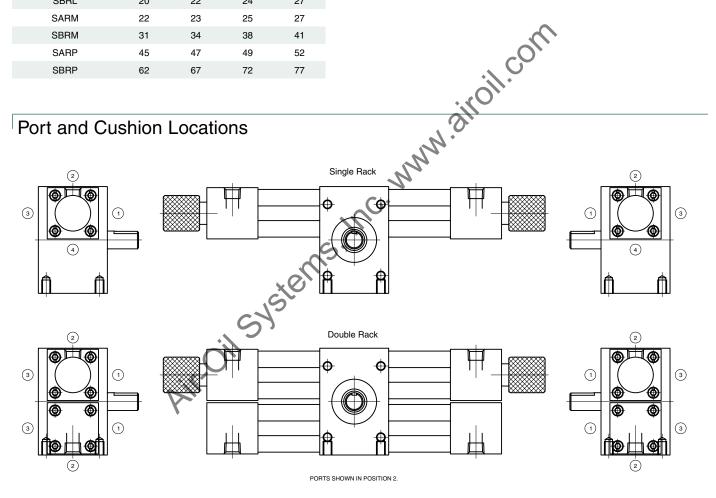
# Unit Weights (lbs)

MODEL	ROTATION (DEGREES)					
WODLL	90	180	270	360		
SARE	3	3	3	3		
SBRE	4	4	4	5		
SARK	9	9	10	10		
SBRK	12	13	14	15		
SARL	14	15	16	17		
SBRL	20	22	24	27		
SARM	22	23	25	27		
SBRM	31	34	38	41		
SARP	45	47	49	52		
SBRP	62	67	72	77		

# **Bearing Load Capacities**

BORE	RADIAL LOAD (lb)	THRUST LOAD (lb)	DISTANCE BETWEEN BEARINGS (in)
1"	100	75	1.40
1 1/2"	300	200	2.15
2"	500	350	2.15
2 1/2"	900	600	2.50
3 1/4"	1300	900	3.75

# Port and Cushion Locations



Standard port location is position 1. Standard cushion location is position 2. Ports and/or cushions in position 4 are only available on single rack rotary actuators.

BORE		PORT	SIZE	
SIZE	1/8	1/4	3/8	1/2
1"	S	Α	=	=
1 1/2"	Α	S	Α	-
2"	Α	S	Α	-
2 1/2"	Α	S	Α	-
3 1/4"	Α	Α	S	Α
S-Standard				

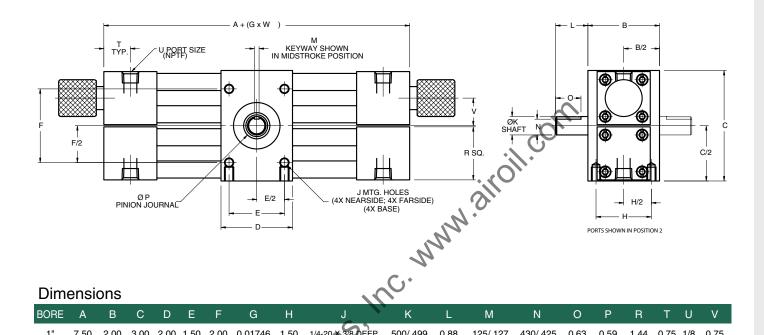
A=Available





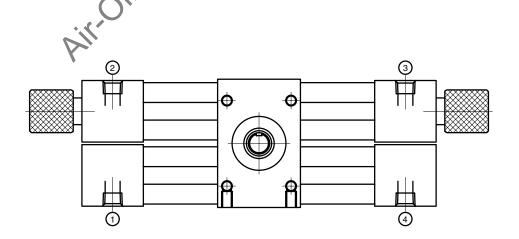
# Multi-position Rotary Actuator 3 Position

Our rotary actuators are available in various multi-position configurations. The following shows 3, 4 and 5 position types. Consult factory.



#### **Dimensions**

BORE	Α	В	С	D	Ε	F	G	Н	J	K	L	М	N	0	Р	R	Т	U	V
1"	7.50	2.00	3.00	2.00	1.50	2.00	0.01746	1.50	1/4-20 X 3/8 DEEP	.500/.499	0.88	.125/.127	.430/.425	0.63	0.59	1.44	0.75	1/8	0.75
1 1/2"	8.50	3.00	4.25	3.00	2.00	3.00	0.02328	2.00	5/16-18 X 1/2 DEEP	.875/.874	1.88	.188/.190	.771/.761	1.50	0.98	2.00	0.75	1/4	1.13
2"	9.50	3.00	5.00	4.00	2.50	3.50	0.03144	2.00	3/8-16 X 1/2 DEEP	1.125/1.124	1.88	.250/.252	.986/.976	1.50	1.18	2.44	0.75	1/4	1.25
2 1/2"	9.75	3.50	6.00	4.00	2.50	4.50	0.03926	2.00	1/2-13 X 3/4 DEEP	1.375/1.374	2.25	.313/.315	1.201/1.191	1.75	1.57	2.94	0.75	1/4	1.5
3 1/4"	11.25	5.00	8.00	5.00	3.00	5.00	0.04800	2.50	3/4-10 X 1 DEEP	1.750/1.749	3.50	.375/.377	1.542/1.532	3.00	1.77	3.75	0.88	3/8	1.94



A three position rotary actuator provides one intermediate stopping position between the full counterclockwise and full clockwise position. The full counterclockwise position is achieved by pressurizing port 1. The intermediate position is achieved by pressurizing both ports 2 and 3. The final clockwise position is achieved by pressurizing port 4. Rotation adjustment for the full counterclockwise and full clockwise positions only are standard.



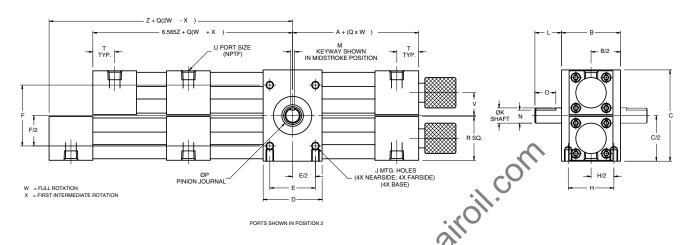




# 4 Position

W° = Full Rotation

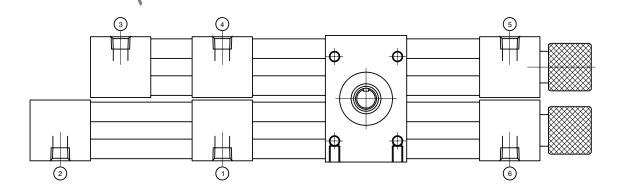
X° = First Intermediate Rotation



#### **Dimensions**

BORE	А	В	С	D	Е	F	Н	J	K	L
1"	3.75	2.00	3.00	2.00	1.50	2.00	1.50	1/4-20 X 3/8 DEEP	.500/.499	0.88
1 1/2"	4.25	3.00	4.25	3.00	2.00	3.00	2.00	5/16-18 X 1/2 DEEP	.875/.874	1.88
2"	4.75	3.00	5.00	4.00	2.50	3.50	2.00	3/8-16 X 1/2 DEEP	1.125/1.124	1.88
2 1/2"	4.88	3.50	6.00	4.00	2.50	4.50	2.00	1/2-13 X 3/4 DEEP	1.375/1.374	2.25
3 1/4"	5.63	5.00	8.00	5.00	3.00	5.00	2.50	3/4-10 X 1 DEEP	1.750/1.749	3.50

М	N	0	X P	Q	R	Т	U	٧	Z
.125/.127	.430/.425	0.63	0.59	0.00872	1.44	0.75	1/8	0.75	6.405
.188/.190	.771/.761	1.50	0.98	0.01164	2.00	0.75	1/4	1.13	6.904
.250/.252	.986/.976	1.50	1.18	0.01571	2.44	0.75	1/4	1.25	7.407
.313/.315	1.201/1.191	1.75	1.57	0.01963	2.94	0.75	1/4	1.50	7.655
.375/.377	1.542/1.532	3.00	1.77	0.02400	3.75	0.88	3/8	1.94	8.660



A four position rotary actuator provides two intermediate stopping positions between the full counterclockwise and full clockwise positions. The full counterclockwise position is achieved by pressurizing port 1. The first intermediate position is achieved by pressurizing both ports 2 and 3. The second intermediate position is achieved by pressurizing both ports 4 and 5. The final position is achieved by pressurizing port 6. Rotation adjustment for the full counterclockwise and full clockwise positions only are standard.



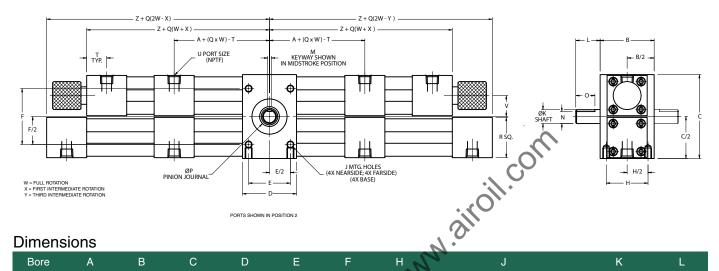


## 5 Position

W° = Full Rotation

= First Intermediate Rotation

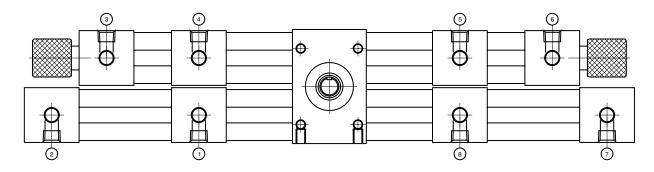
= Third Intermediate Rotation



#### **Dimensions**

Bore	Α	В	С	D	E	F	H	J	K	L
1"	3.75	2.00	3.00	2.00	1.50	2.00	1150	1/4-20 X 3/8 DEEP	.500/.499	0.88
1 1/2"	4.25	3.00	4.25	3.00	2.00	3.00	2.00	5/16-18 X 1/2 DEEP	.875/.874	1.88
2"	4.75	3.00	5.00	4.00	2.50	3.50	2.00	3/8-16 X 1/2 DEEP	1.125/1.124	1.88
2 1/2"	4.88	3.50	6.00	4.00	2.50	4.50	2.00	1/2-13 X 3/4 DEEP	1.375/1.374	2.25
3 1/4"	5.63	5.00	8.00	5.00	3.00 -	5 00	2 50	3/4-10 X 1 DEEP	1 750/1 749	3.50

M	N	0	XP.	Q	R	T	U	V	Z
.125/.127	.430/.425	0.63	0.59	0.00872	1.44	0.75	1/8	0.75	6.405
.188/.190	.771/.761	1.50	0.98	0.01164	2.00	0.75	1/4	1.13	6.904
.250/.252	.986/.976	1.50	1.18	0.01571	2.44	0.75	1/4	1.25	7.407
.313/.315	1.201/1.191	1.75	1.57	0.01963	2.94	0.75	1/4	1.50	7.655
.375/.377	1.542/1.532	3.00	1.77	0.02400	3.75	0.88	3/8	1.94	8.660



A five position rotary actuator provides three intermediate stopping positions between the full counterclockwise and full clockwise positions. The full counterclockwise position is achieved by pressurizing port 1. The first intermediate position is achieved by pressurizing both ports 2 and 3. The second intermediate position is achieved by pressurizing both ports 4 and 5. The third intermediate position is achieved by pressurizing both ports 6 and 7. The final clockwise position is achieved by pressurizing port 8. Rotation adjustment for the full counterclockwise and full clockwise positions only are standard.





# R series Switches

# R series Global Switch

			Switches					
Cylinders	Bore		RSS02	RSQ02	HPNPS31	HPNPQ31	HNPNS32	HNPNQ32
R series	All	Bracket	Direct Fit w/included adapter	Direct Fit w/included adapter	Direct Fit w/included adapter	Direct Fit w/included adapter	Direct Fit w/included adapter	Direct Fit w/included adapter

## R series World Switch

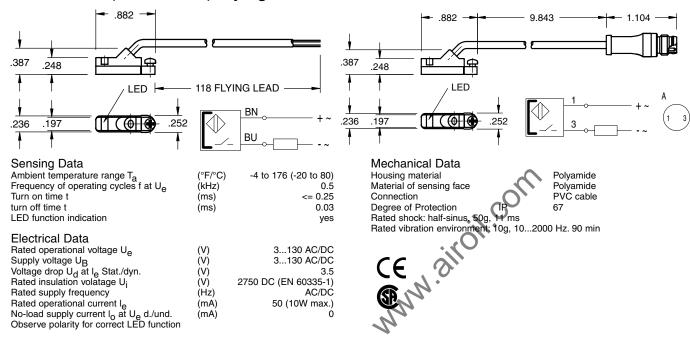
			Switches					
Cylinders	Bore		SR6-002	SR6-022	SH6-021	SH6-031	SH6-022	SH6-032
R series	All	Bracket	Direct Fit					
NOTE: See page 17 f	or dimensional and t	echnical data	a	NN'	N.SII.			
		50	We'll	Q				
	All  For dimensional and t	57						



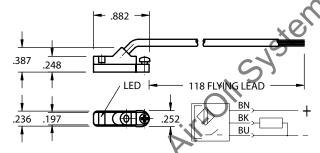


# R series Global Switches

Reed Switch (AC/DC NO), flying lead - RSS02, 8mm connector - RSQ02

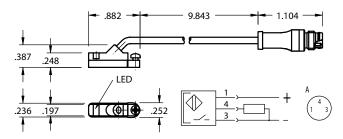


# Electronic Switch (PNP NO), flying lead - HPNPS31, 8mm connector - HPNPQ31



Sensing Data	•	
Ambient temperature range d	(°F/°C)	-13 to +158 (-25 to +70)
Temperature drift	(% of )	<= 0.3%/°C
Frequency of operating cycles f at Up	(kHz)	10
Turn on time t	(ms)	.05
turn off time t	(ms)	.05
Utilization categories		DC13
Function-/supply voltage indication		YES

Function-/supply voltage indication		YES
Electrical Data	44	04.50
Rated operational voltage U <sub>e</sub>	(V)	24 DC
Supply voltage U <sub>B</sub>	(V)	1030 DC
incl. ripple	(% of U <sub>P</sub> )	15
Voltage drop U <sub>d</sub> at I <sub>e</sub> Stat./dyn.	(V)	1/-
Rated insulation volatage Ui	(V)	75 AC
Rated supply frequency	(Hz)	DC
Rated operational current I <sub>P</sub>	(mA)	200
No-load supply current Io at Ue d./und.	(mA)	25/13
Protected against polarity reversal		YES



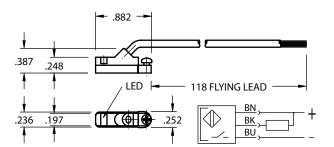
Mechanical Data		
Housing material		Polyamide
Material of sensing face		Polyamide
Connection		PVC cable
Degree of Protection	ΙP	67
Rated shock: half-sinus, 30	g, 11 ms	
Rated vibration environmen	nt: 55 Hz 1	mm amplitude 3 x 3

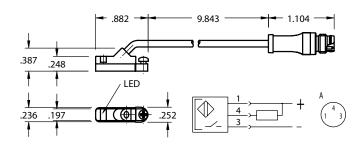






# Electronic Switch (NPN NO), flying lead - HNPNS32, 8mm connector - HNPNQ32





Sensing Data Ambient temperature range d Temperature drift Frequency of operating cycles f at Up Turn on time t turn off time t Utilization categories

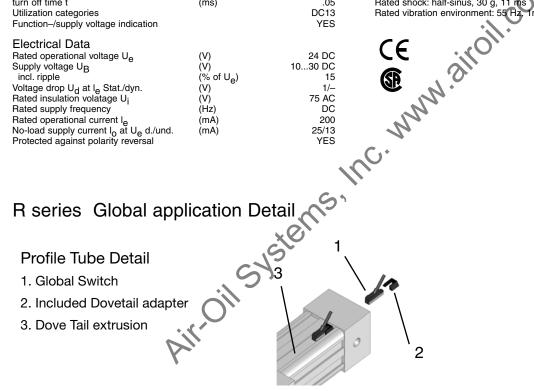
(°F/°C) (% of S <sub>r</sub> ) (kHz) (ms) (ms)	-13 to +158 (-25 to +70 <= 0.3%/°C 10 .05 .05 DC13
	YES

# Mechanical Data

Housing material
Material of sensing face Connection Degree of Protection Rated shock: half-sinus, 30 g, 11 ms Rated vibration environment: 55 Hz

Polyamide Polyamide PVC cable

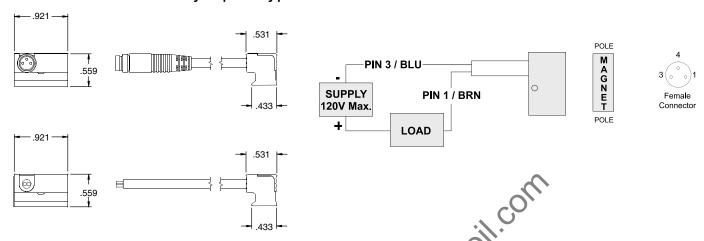
1mm amplitude, 3 x 30





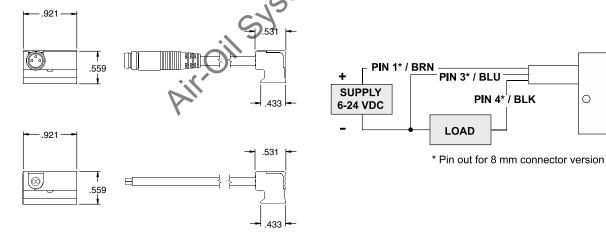


# R Series World Switches Reed Switch - Normally Open Type SR6



P/N	Switch Style	Switch Type	Function	Switching Voltage	Switching Current	Switching Power	Voltage Drop
SR6-002	3m Wire Version	Reed Switch, LED	SPST Normally Open	5 -120V AC/DC	0.025 Amps Max. 0.001 Amps Min.	3 Watts Max.	3.5 Volts
SR6-004	3m Wire Version	Reed Switch, LED & MOV	SPST Normally Open	5 -120V AC/DC	0.5 Amps Max. 0.005 Amps Min.	10 Watts Max.	3.0 Volts
SR6-021	8mm Pigtail	Reed Switch	SPST Normally Open	0 -120V AC/DC	0.5 Amps Max.	10 Watts Max.	0 Volts
SR6-022	8mm Pigtail	Reed Switch, LED	SPST Normally Open	5 -120V AC/DC	0.025 Amps Max. 0.001 Amps Min.	3 Watts Max.	3.5 Volts
SR6-024	8mm Pigtail	Reed Switch, LED & MOV	SPST Normally Open	5 -120V AC/DC	0.5 Amps Max. 0.005 Amps Min.	10 Watts Max.	3.0 Volts

# Hall Effect Switch - Sourcing Type SH6



P/N	Switch Style	Switch Type	Function	Switching Voltage	Switching Current	Switching Power	Voltage Drop
SH6-031	3m Wire Version	Hall Effect for Reed Magnet & Light Sourcing	Normally Open Sourcing (PNP)	6 -24 VDC	0.3 Amps Max.	7.2 Watts Max.	0.5 Volts
SH6-021	8m Connector Pigtail	Hall Effect for Reed Magnet & Light Sourcing	Normally Open Sourcing (PNP)	6 -24 VDC	0.3 Amps Max.	7.2 Watts Max.	0.5 Volts

POLE

М

AGNET

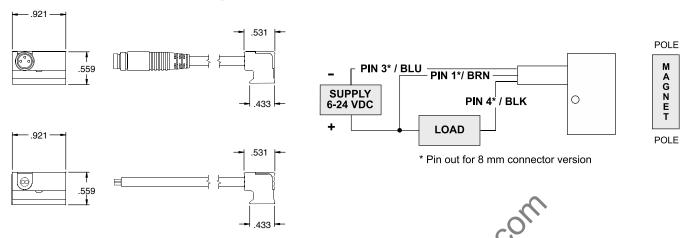
POLE

0





# Hall Effect Switch - Sinking Type SH6

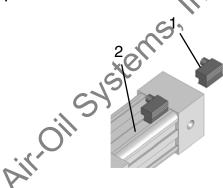


P/N	Switch Style	Switch Type	Function	Switching Voltage	Switching Current	Switching Power	Voltage Drop
SH6-032	3m Wire Version	Hall Effect for Reed Magnet & Light Sourcing	Normally Open Sourcing (NPN)	6 -24 VDC	0.3 Amps Max.	7.2 Watts Max.	0.5 Volts
SH6-022	8m Connector Pigtail	Hall Effect for Reed Magnet & Light Sourcing	Normally Open Sourcing (NPN)	6 -24 VDC	0.3 Amps Max.	7.2 Watts Max.	0.5 Volts

R series World application Detail

# Profile Tube Detail

- 1. World Switch
- 2. Dove Tail extrusion



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